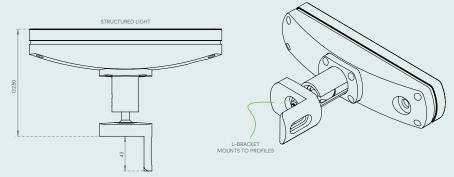
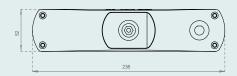
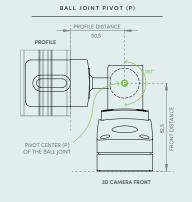
Edu kit facts

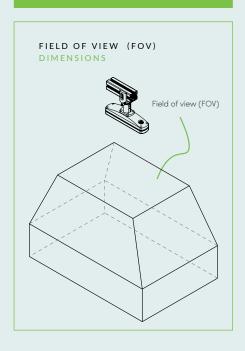


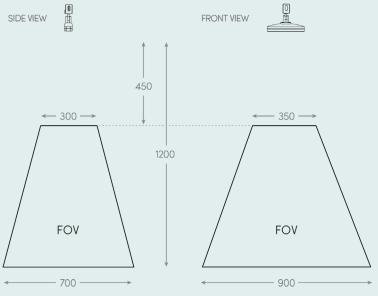


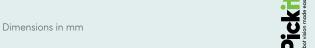


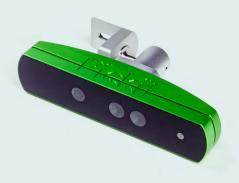












CAMERA TECHNICAL SPECIFICATIONS

| 3D measurement method | Structured light |
|---|-------------------------------------|
| Image processing speed | 300 ms |
| 3D camera resolution (px) | 640x480 |
| 3D camera precision (mm)* | 0.6 - 1.6 mm |
| 3D camera weight | 1030 g |
| 3D camera accuracy (%) | < 1.2% |
| 3D camera accuracy (mm)** | 2 - 6 mm |
| Estimated picking accuracy*** | 1.5 - 2 x 3D camera accuracy |
| 3D camera weight | 1030 g |
| 3D camera connection to PC | M12-8 (USB) - USB3 |
| PC connection to robot | TCP/IP over Ethernet |
| Power supply | USB3 5VDC |
| Temperature | 5°C to 40°C |
| Humidity | 95% @ 40°C (non-condensing |
| IP rating | IP 54 |
| Vibrations | Operating, 2 Grms, 5–500 Hz, 3 axes |
| Conforms to | CE, FCC |
| * A larger distance from the expert has lower 2D expert presision | |

- * A larger distance from the camera has lower 3D camera precision
- ** A larger FOV has lower 3D camera accuracy
- *** Average accuracy from the real production environment



WORKS WITH ROS DOCS.PICKIT3D.COM/ROS

:::ROS

FANUC

OPTIONAL: USE PICKIT WITH THE ROBOT OF YOUR CHOICE

KUKA





STÄUBLI









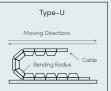




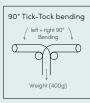
10m / 20m

High-Flex / Continuous-Flex

- Type-U (R= 67,5mm 5.000.000 times)
- <u>Type-S</u> (R= 60mm 1.000.000 times)
- 90° Tick-Tock bending (R= 60mm 1.000.000 times)







PROCESSOR

Power consumption

- While turned off: 3W
- Booting: 35W
- Idle: 25W
- Heavy processing: 85W

Technical specifications

- Processor: 6 cores (12 threads) at 3.7 Ghz
- 19 inch server: rack compatible (1U)
- Temperature: 5°C to 40°C
- Vibrations: Operating, 1Grms (HDDx1); 3 Grms (SSD x 1)
- IP rating: IP20
- Humidity: 10-85% @ 40°C
- Weight: 2,5 kg

YASKAWA

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